**RECOMMENDATIONS FOR REFERENCES**

**REFERENCES SHOULD BE FORMATTED AS FOLLOWS:**

**BOOK**

1.**Author’s Name**,

2. Title of Book, (2a) (Translation of Non-English Title),

3. Editor(s),

4. City,

5. Publisher,

6. year of publication,

7. edition [if not first].

**Richards, M.A., Scheer, J.A., and Holm, W.A.**, Principles of Modern Radar: Basic Principles, SciTech Publishing, 2010, second edition.

**Brockhaus, R., Alles, W., and Luckner, R.**, Flugregelung (Flight Control), Berlin, Springer Verlag, 2011.

**JOURNAL**

1. **Author’s Name,**

2. Title of Paper in English,

3. Title of Journal,

4. year of publication,

5. volume number,

6. issue number,

7. page number(s).

**Mohammed, A.H. and Schwarz, K.P.**, Adaptive Kalman Filtering for INS/GPS, Journal of Geodesy, 1999, vol. 73, pp. 193–203.

**Korkishko, Yu.N, Fedorov, V.A., and Prilutskii, V.E.**, Precision Fiber Optic Gyroscope with Digital Linear Output, Giroskopiya i Navigatsiya, 2004, no. 1, pp. 69–82.

**MEETING PAPERS**

1.**Author’s Name,**

2. Title of Paper,

3. Name of Meeting or Conference, (3a) (Translation of Non-English Name),

4. City,

5. Publisher,

6. year,

7. page number(s).

**Meyer, D. and Larsen, M.**, Nuclear Magnetic Resonance Gyro for Inertial Navigation, 20th St. Petersburg International Conference on Integrated Navigation Systems, St. Petersburg, CSRI Elektropribor, 2013, pp. 156–162.

**PATENT**

1. **Name of Patent Holder,**

2. Number of Patent or Inventor’s Certificate,

3. year of patent or publication.

**Leete, B.D.**, U.S. Patent 2,720,625, 1955.

**THESIS**

1. **Author’s Name,**

2. Title of Thesis in English,

3. Master/PhD Thesis,

4. City,

5. Publisher,

6. year of publication,

7. page number(s).

**Johnson, E.N.**, Limited Authority Adaptive Flight Control, PhD thesis, Georgia University of Technology, 2000.